

Biped Locomotion: Dynamics, Stability, Control And Application (Communications And Control Engineering / Scientific Fundamentals Of Robotics) **By Miomir Vukobratovic;Branislav Borovac;Dusan Surla**

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Stable adaptive control of a bipedal walking; Cartesian virtual dynamics space; Lyapunov method; adaptive control; asymptotic stability; bipedal robot; locomotion

Author: Miomir Vukobratovic, Branislav Borovac, Dusan Surla, Dragan Stokic,
Title: Biped Locomotion: Dynamics, Stability, Control and Application
(Communications and

Modeling, stability and control of biped robots. The role of impact in the stability of bipedal locomotion. Dynamics and Stability of Systems, 1 (3)

Dynamics of Biped Locomotion Professor Miomir Vukobratovi D. Sc., Ph. D.
Stability and Dynamic Control of Certain Types of Biped Locomotion ,

The focus of this survey is the modeling and control of bipedal locomotion systems. Next, we consider the dynamic stability of bipedal gait.

A general approach based on discrete mapping techniques is presented to study stability of bipedal locomotion. Dynamic Systems & Control

Here for the first time in one book is a comprehensive and systematic approach to the dynamic modeling and control of biped locomotion robots.

Control of a Dynamical Biped Locomotion System for Steady A dynamic biped locomotion robot which realizes high speed movement is Stability; Control equipment;

Zero moment point is a concept related with dynamics and control of legged locomotion, stability region and the motion of motion of the biped

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B. Borovac, D. Surla and D. Stokic, Biped Locomotion: Dynamics, Stability, Design, Dynamic Modification, and Adaptive Control of a New Biped Walking Robot.

Biped Locomotion Dynamics, Stability, Control and Application (Communications and Control Engineering) by Miomir Vukobratovic, Branislav Borovac, Dusan Surla, Stok

Here for the first time in one book is a comprehensive and systematic approach to the dynamic modeling and control of biped locomotion robots.

Strategies for dynamic stability during adaptive human locomotion to stability. Biped locomotion during locomotion. Control of stability and

b Department of Biomedical Engineering, University of Michigan, Ann Arbor, Locomotion; Exoskeleton; Gait; control, we set the threshold

design and more relaxed control of passive dynamics motion, McGeer's early passive-dynamic stability in some settings. Passive dynamics is

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Vukobratovic M, Borovac B, Surla D, Stokic D. Biped locomotion: Dynamics, stability, control and application. An application to biped locomotion control;

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Optimal Constrained Balancing Control of a on Fluid Power and Motion Control; ASME 2011 Dynamic Systems and control is important for biped locomotion.